

Nature of roll to spiral-defect-chaos transition

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We investigate the nature of the parallel-roll-to-spiral-defect-chaos (SDC) transition in Rayleigh-Bénard convection, based on the generalized Swift-Hohenberg model. We carry out extensive, systematic numerical studies by, on one branch, increasing the control parameter gradually from the parallel-roll regime to the SDC regime and, on the other branch, decreasing it in the opposite manner. We find that the data of several time-averaged *global* quantities all form hysteretic loops from the two branches. We also discuss several possible scenarios for the transition and analyze our data for SDC accordingly. We conclude that the roll-to-SDC transition is first order in character and that the correlation length diverges at the conduction to convection onset. We further postulate that this transition can be understood somewhat similarly to the hexagon-to-roll transition in non-Boussinesq fluids. Finally, we comment on the differences between our conclusion and those in two experiments. [S1063-651X(98)08502-X]

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I. INTRODUCTION

Many nonequilibrium systems exhibit self-organized pattern-forming phenomena [1]. In the past few years, a different type of intrinsic pattern has emerged in many disciplines of science. These patterns are characterized by their extensive, irregular behavior in both space and time, which are known as spatiotemporal chaos (STC) [1]. STC typically exists in large size systems and its complexity increases dramatically with the system size [2]. Owing to its generic dynamical complexity, STC hence poses a great challenge to both experimentalists and theoreticians.

From the very beginning, Rayleigh-Bénard convection (RBC) has been a paradigm in the study of pattern formation in driven dissipative systems because of its relative simplicity and high precision in controlled experiments [3]. RBC can occur when a thin horizontal layer of fluid is heated from below. The system is described by three dimensionless parameters [1]: (a) the Rayleigh number $R \equiv g \alpha d^3 \Delta T / \kappa \nu$, in which g is the gravitational acceleration, d the layer thickness, ΔT the temperature gradient across the layer, α the thermal expansion coefficient, κ the thermal diffusivity, and ν the kinematic viscosity; (b) the Prandtl number $\sigma \equiv \nu / \kappa$; and (c) the aspect ratio $\Gamma \equiv L / 2d$, where L is the horizontal size of the system. The Rayleigh number R is the control parameter of the system; the Prandtl number σ specifies the fluid properties. It is convenient to introduce a reduced control parameter $\epsilon \equiv (R - R_c) / R_c$, where R_c is the critical value of R at which the fluid bifurcates from a static conductive state to a convective state.

RBC has been studied extensively in the literature [1,3]. Theoretical analyses by Busse and his coauthors [4] predict that parallel roll states are stable inside a stability domain in (R, k, σ) space with k the wave number, which is known as the ‘‘Busse balloon.’’ Surprisingly, recent experiments [5,6] and numerical studies [7–9], using systems with $\sigma \sim O(1)$ and large Γ , revealed that the parallel roll state yields to a spatiotemporally chaotic state even for states inside the Busse balloon. This spatiotemporally chaotic state, called

spiral-defect-chaos (SDC), exhibits very complicated dynamics, illustrated by the interplay of numerous rotating spirals, patches of moving rolls, intricate grain boundaries, dislocations, and other defects [5,6]. Its discovery has since stimulated many experimental [5,6,10–12], theoretical [13,14], and numerical [7–9,15] efforts to understand it.

The nature of the parallel roll to SDC transition is one of the important questions with respect to SDC and has been investigated in several experimental and numerical studies [11,12,15]. By solving the generalized Swift-Hohenberg (GSH) model of RBC [16–18] for non-Boussinesq fluids with *random* initial conditions, two of us [15] characterized the transition by the behavior of time-averaged global quantities such as convective current J , vorticity current Ω (called vortex energy in Ref. [15]), and spectra entropy Ξ [19]. It was found that the convective current seems to be smooth across the transition temperature ϵ_T , but both the vorticity current and the spectra entropy seem to obey power-law behavior near ϵ_T . However, this study was unable to distinguish between a gradual or sharp transition. Despite its inconclusiveness on the nature of the roll-to-SDC transition, this study suggests that studying such time-averaged global quantities is quite useful. It hence motivated us to develop a phenomenological theory for STC, including SDC, in RBC [14]. In the theory, we made a random-phase approximation for the spatiotemporally chaotic states and assumed that their time-averaged structure factor $S(k)$ satisfies a scaling form with respect to the two-point correlation length ξ_2 . With these assumptions, we obtained analytical expressions for both J and Ω in terms of measurable quantities. These theoretical results provide us some insights on the nature of SDC. In addition, a recent experimental study [12] also found spectra entropy Ξ to be a useful quantity.

On the experimental side, Morris *et al.* [11] studied the structure of SDC using a *circular* cell. They found that the correlation length ξ_2 is smooth across ϵ_T and diverges at $\epsilon = 0$ with a mean-field exponent. However, the data for the correlation time τ was consistent with either a divergence at ϵ_T with a mean-field exponent or a divergence at $\epsilon = 0$ with

a non-mean-field exponent. However, Cakmur *et al.* [12] recently used a *square* cell in their experiment and found that ξ_2 diverges at ϵ_T with a small exponent. In critical phenomena, we know that finite (infinite) ξ_2 and τ are normally associated with first-order (second-order) transitions. If this is also true in nonequilibrium phenomena, then these two experiments should lead to different conclusions about the nature of the roll-to-SDC transition at ϵ_T . We will comment further about these two experiments in Sec. V.

In this paper we present our extensive, systematic numerical studies of SDC, based on the GSH model of RBC for Boussinesq fluids. In comparison with studies in Ref. [15], we use random initial conditions at $\epsilon=0.05$ and $\epsilon=0.8$ only. Then, after completing the calculation at one ϵ , we increase ϵ (originally from $\epsilon=0.05$) or decrease ϵ (originally from $\epsilon=0.8$) gradually and take the final state from the previous ϵ as our initial condition. We hence obtain two different branches of data, one from increasing ϵ and the other from decreasing ϵ . We find that the results for ξ_2 , J , Ω , and Ξ all form hysteretic loops from the two branches during the roll-to-SDC transition. We analyze our data in accordance with our theoretical results [14]. We conclude that the roll-to-SDC transition is first order in character. We also postulate that this transition can be understood somewhat similarly to the hexagon-to-roll transition in non-Boussinesq fluids [20]; namely, we postulate that the SDC bifurcation actually occurs at $\epsilon=0$. However, since SDC is unstable (or metastable) against parallel roll states at smaller ϵ , it emerges only for $\epsilon > \epsilon_T$.

This paper is organized as follows. In Sec. II we introduce the GSH model of RBC and define some important time-averaged global quantities. We then summarize our theoretical results in Ref. [14]. In Sec. III we discuss possible scenarios with regard to SDC, according to whether the correlation length ξ_2 diverges at $\epsilon=0$ or at ϵ_T . We also note that one might expect τ to have a power-law behavior, similar to that of ξ_2 , and speculate that a scaling relation exists between the exponents of ξ_2 and τ . Furthermore, we speculate that the structure factor $S(k, \omega)$, defined in Ref. [11], satisfies a scaling form $S(k, \omega) = \xi_2 \mathcal{F}((k - k_{max}) \xi_2, \omega \tau)$, which is more general than that of the time-averaged $S(k)$. We present the details of our numerical studies in Sec. IV. We also analyze the data for ξ_2 , J , Ω , and Ξ to test these different scenarios. In Sec. V we discuss the subtleties involved in determining the nature of the roll-to-SDC transition and comment on the different conclusions between this work and the earlier experimental studies [11,12].

II. THEORETICAL RESULTS

The GSH model of RBC [16–18] is widely accepted for theoretical study. This model is derived from the three-dimensional hydrodynamic equations, but is much simpler to study both numerically and analytically. The GSH model contains two coupled equations in two-dimensional space $\mathbf{r} = (x, y)$, one for the order parameter $\psi(\mathbf{r}, t)$ and the other for the mean-flow field $\zeta(\mathbf{r}, t)$. The convective patterns in RBC are completely determined by the order parameter $\psi(\mathbf{r}, t)$. The amplitude equations for the GSH model and the hydrodynamical equations are the same in the leading order near onset. Numerical solutions of this model or its modified ver-

sions have not only reproduced most patterns observed in experiments but also resembled experimental results relatively well [1,7,8,13,15,21]. However, there are some shortcomings in the model [9,22]: The stability boundary of the model does not coincide with that of hydrodynamics; it induces an unphysical, short-ranged cross roll instability; and both the shape and the peak position of the power spectrum for SDC are different from those in the real system. Even so, owing to its simplicity and its qualitative resemblance to real systems, this model is very valuable in studying RBC.

In the GSH model, the order parameter $\psi(\mathbf{r}, t)$ satisfies [16–18]

$$\partial_t \psi + g_m \mathbf{U} \cdot \nabla \psi = [\epsilon - (\nabla^2 + 1)^2] \psi - \psi^3, \quad (1)$$

where ∇ is the gradient operator in two dimensions and $\mathbf{U}(\mathbf{r})$ is the mean-flow velocity given by $\mathbf{U}(\mathbf{r}) = \nabla \zeta(\mathbf{r}, t) \times \mathbf{e}_z$. The mean-flow field $\zeta(\mathbf{r}, t)$, on the other hand, satisfies [18]

$$[\partial_t - \sigma(\nabla^2 - c^2)] \nabla^2 \zeta = \mathbf{e}_z \cdot [\nabla(\nabla^2 \psi) \times \nabla \psi]. \quad (2)$$

Variables in these equations have been rescaled for numerical convenience. Their relations to their physical values can be found in Ref. [14]. [See Eqs. (1)–(3) and (58)–(60) therein.] For example, the reduced Rayleigh number ϵ in Eq. (1) is related to its physical value ϵ_{expt} by $\epsilon_{expt} = 0.3594\epsilon$. The rescaling factors for ψ , ζ , t , and \mathbf{r} and parameters g_m , σ , and c^2 can also be found in Ref. [14].

We now define several important time-averaged *global* quantities in RBC. The first one is the time-averaged convective current defined as

$$J \equiv A^{-1} \int d\mathbf{r} \overline{\psi^2(\mathbf{r}, t)} = \sum_{\mathbf{k}} \overline{\hat{\psi}^*(\mathbf{k}, t) \hat{\psi}(\mathbf{k}, t)}, \quad (3)$$

where $\hat{\psi}(\mathbf{k}, t)$ is the Fourier component of $\psi(\mathbf{r}, t)$, A is the area of the system, and $\overline{F(t)}$ represents the time average of $F(t)$. This quantity increases from $J=0$ to $J>0$ at the conduction-to-convection onset and hence characterizes the transition. The second one is the time-averaged vorticity current defined as

$$\Omega \equiv A^{-1} \int d\mathbf{r} \overline{\omega_z^2(\mathbf{r}, t)}, \quad (4)$$

where $\omega_z(\mathbf{r}, t) = -\nabla^2 \zeta(\mathbf{r}, t)$. This quantity reflects the distortion of patterns at large distance. It is identically zero for perfect parallel rolls and increases dramatically for SDC [15]. Because of this, it has been speculated that one may take Ω as one of the order parameters to characterize the roll-to-SDC transition [15]. The third one is the time-averaged spectra entropy defined as [19]

$$\Xi \equiv - \sum_{\mathbf{k}} \overline{S(\mathbf{k}, t) \ln S(\mathbf{k}, t)}, \quad (5)$$

where the structure factor $S(\mathbf{k}, t)$ is given by

$$S(\mathbf{k}, t) = \hat{\psi}^*(\mathbf{k}, t) \hat{\psi}(\mathbf{k}, t) / J. \quad (6)$$

Like its counterpart in thermodynamics, the spectra entropy Ξ is related to the randomness of all excited states. Its value

is $\ln 2 = 0.6931$ for perfect parallel roll states, but increases dramatically for SDC. This quantity was also found useful to characterize the roll-to-SDC transition [12,15]. Another important quantity is the two-point correlation length defined as

$$\xi_2 = [\langle k^2 \rangle_{\mathbf{k}} - \langle k \rangle_{\mathbf{k}}^2]^{-1/2}, \quad (7)$$

where we have used the notation $\langle F(\mathbf{k}) \rangle_{\mathbf{k}} = \sum_{\mathbf{k}} F(\mathbf{k}) S(\mathbf{k})$ in which $S(\mathbf{k})$ is the time-averaged structure factor. It was found that $S(\mathbf{k})$ is azimuthally uniform for SDC [5,15]. So one may define an azimuthally averaged structure factor $S(k)$, normalized by $\int_0^\infty dk k S(k) = 1$, and its corresponding average $\langle F(k) \rangle_k = \int_0^\infty dk k S(k) F(k)$.

In Ref. [14] we presented our analytical calculations, using the GSH model, of J and Ω for STC in RBC. These calculations are valid for both SDC and phase turbulence (PT) [23,24]. By assuming that the time-averaged two-point correlation function

$$C(\mathbf{r}_1, \mathbf{r}_2) \equiv \overline{\psi(\mathbf{r}_1, t) \psi(\mathbf{r}_2, t) / \psi^2(\mathbf{r}_1, t)} \quad (8)$$

is translation invariant in STC, i.e., $C(\mathbf{r}_1, \mathbf{r}_2) = C(\mathbf{r}_1 - \mathbf{r}_2)$, we found that the phases of two $\hat{\psi}(\mathbf{k}, t)$ fields are uncorrelated in time unless they have the same wave number \mathbf{k} . Furthermore, we applied a *random-phase approximation* (RPA) to STC in which four-point correlation functions are approximated by products of two-point correlation functions such as $\overline{\psi \psi \psi \psi} \sim \overline{\psi \psi} \overline{\psi \psi}$. Using this RPA, we derived J and Ω in terms of $S(k)$. We further assumed that the structure factor satisfies a *scaling* form with respect to ξ_2 , i.e.,

$$kS(k) = \xi_2 \mathcal{F}((k - k_{max}) \xi_2), \quad (9)$$

where k_{max} is the peak position of $kS(k)$ and $\mathcal{F}(x)$ is the scaling function satisfying $\int_{-\infty}^\infty dx \mathcal{F}(x) = 1$. [Since $k \geq 0$ in $kS(k)$, the lower limit for $\mathcal{F}(x)$ is $-k_{max} \xi_2$, which we approximate by $-\infty$.] From these assumptions, we obtained explicit formulas for both J and Ω in the leading order of ξ_2^{-1} . For SDC, these results can be written as [14]

$$J_{SDC}^{SH} \approx \frac{2}{3} \left[\epsilon - \frac{4 \langle x^2 \rangle_x}{\xi_2^2} \right] \quad (10)$$

and

$$\Omega_{SDC}^{SH} \approx \frac{1}{2\sigma^2} \left[\frac{2+c^2}{\sqrt{4c^2+c^4}} - 1 \right] \frac{(J_{SDC}^{SH})^2}{\xi_2^2}, \quad (11)$$

where we have used the notation $\langle F(x) \rangle_x = \int_{-\infty}^\infty dx \mathcal{F}(x) F(x)$. Inserting $k = k_{max} + x \xi_2^{-1}$ and Eq. (9) into Eq. (7), it is easy to see that $\langle x^2 \rangle_x = 1 + \langle x \rangle_x^2 \geq 1$ and $\langle k \rangle_k = k_{max} + \xi_2^{-1} \langle x \rangle_x$.

In comparison, the convective current for perfect parallel rolls with wave number k_0 has been evaluated to be $J_{roll}^{SH} = \frac{2}{3} [\epsilon - (1 - k_0^2)]$ [17]. To our knowledge, there is no explicit formula for J_{roll}^{SH} for distorted rolls. If one uses this expression for J_{roll}^{SH} but replaces $(1 - k_0^2)^2$ with $\langle (1 - k^2)^2 \rangle_{\mathbf{k}}$ to account for the finite width of the power spectrum, one finds for distorted roll states that

$$J_{roll}^{SH} = \frac{2}{3} \left[\epsilon - \frac{4 \langle x^2 \rangle_x}{\xi_2^2} \right], \quad (12)$$

where ξ_2 and $\langle x^2 \rangle_x$ have exactly the same meanings as in Eq. (10), but their values may be different.

Notice that the formulas for J_{SDC}^{SH} and J_{roll}^{SH} are the same. This, however, is due to the simplification that the coupling constant of the nonlinear term ψ^3 is taken as a constant in Eq. (1). In a more realistic description of hydrodynamics, this coupling constant, say $g(\cos \alpha)$, is angle dependent and has been evaluated in Ref. [17] [before the rescalings leading to Eq. (1)]. For such a coupling constant, the time-averaged convective current for SDC, before the rescalings, has been calculated in Ref. [14] as

$$J_{SDC} \approx \frac{2}{g_{SDC}} \left[\epsilon - \frac{\langle x^2 \rangle_x \xi_0^2}{\xi_2^2} \right], \quad (13)$$

where $\xi_0^2 \approx 0.148$ [17] and $g_{SDC} = 1.1319 + 0.0483\sigma^{-1} + 0.0710\sigma^{-2}$ [14]. Correspondingly, the convective current for parallel rolls is

$$J_{roll} = \frac{1}{g_{roll}} \left[\epsilon - \frac{\langle x^2 \rangle_x \xi_0^2}{\xi_2^2} \right], \quad (14)$$

with $g_{roll} = 0.6995 - 0.0047\sigma^{-1} + 0.0083\sigma^{-2}$ [17]. From these expressions, one finds that

$$\begin{aligned} \Delta J \equiv J_{SDC} - J_{roll} &= \left[\frac{2}{g_{SDC}} - \frac{1}{g_{roll}} \right] \epsilon - \frac{2\xi_0^2}{g_{SDC}} \left[\frac{\langle x^2 \rangle_x}{\xi_2^2} \right]_{SDC} \\ &+ \frac{\xi_0^2}{g_{roll}} \left[\frac{\langle x^2 \rangle_x}{\xi_2^2} \right]_{roll}. \end{aligned} \quad (15)$$

Since $2/g_{SDC}$ is not equal to $1/g_{roll}$ for most values of σ , the first term above is not zero. It is highly unlikely that this term may be canceled by the contributions from the two other terms. Thus there exist discontinuities in the value and the slope of J during the roll-to-SDC transition. This is not surprising considering that J depends sensitively on the structure of the convective pattern [17] and that the structures of parallel rolls and SDC are so different. Assuming $[\langle x^2 \rangle_x / \xi_2^2]_{SDC} = [\langle x^2 \rangle_x / \xi_2^2]_{roll}$ at the transition temperature, we find that $\Delta J / J_{roll} = 0.1239$ for $\sigma = 1$. So the value and the slope of J jump about 10% during the roll-to-SDC transition. Similar jumps can be found for other values of σ under the same assumption; see Fig. 1.

III. POSSIBLE SCENARIOS

From Eqs. (10) and (11), it is obvious that the behavior of J_{SDC} and Ω_{SDC} depend sensitively on the two-point correlation length ξ_2 . For simplicity, we drop the superscripts in Eqs. (10)–(12). We assume that ξ_2 has a power-law behavior such as

$$\xi_2 \approx \xi_{2,0} \tilde{\epsilon}^{-\nu}, \quad (16)$$

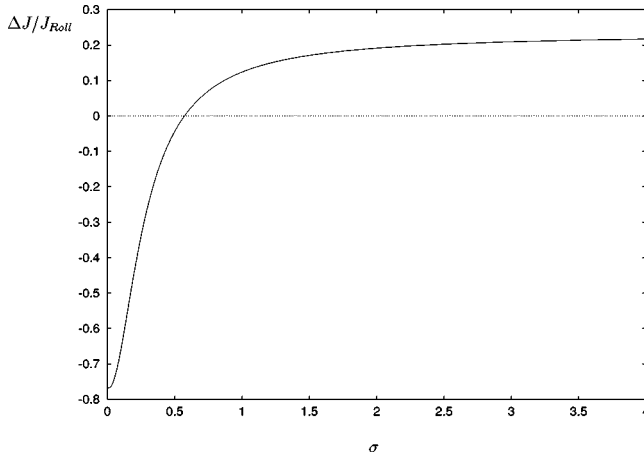


FIG. 1. $\Delta J/J_{roll}$ vs Prandtl number σ , where $\Delta J = J_{SDC} - J_{roll}$.

where $\tilde{\epsilon}$ is the basic scaling field for SDC. Similar behavior has been found for ξ_2 in PT [14]. In that case, since the transition to PT occurs at $\epsilon = 0$ [23,24], one has simply $\tilde{\epsilon} = \epsilon$ [14]. The possible scenario for SDC, however, is more subtle since the roll-to-SDC transition occurs at a positive temperature ϵ_T [5–7]. One obviously has two alternative choices for the scaling field $\tilde{\epsilon}$ in Eq. (16): (A) $\tilde{\epsilon} = \epsilon$ or (B) $\tilde{\epsilon} = \epsilon - \epsilon_T$. Case (A) is similar to the situation in the hexagon-to-roll transition [20] where the two-point correlation length ξ_2 is finite at the transition temperature ϵ_T but diverges at $\epsilon = 0$. This scenario is consistent with the experimental result by Morris *et al.* [11]. Case (B) resembles the situation in critical phenomena in which ξ_2 diverges at ϵ_T . This scenario was suggested by Cakmur *et al.* [12]. We now discuss these two scenarios separately.

(A) $\tilde{\epsilon} = \epsilon$. This implies that all properties of SDC are controlled at $\epsilon = 0$ rather than at $\epsilon = \epsilon_T$. As far as scaling relations are concerned, this case is similar to the situation in PT [14]. Similar to those in PT, one may hence define power laws such as

$$J_{SDC} \approx J_0 \epsilon^\mu, \quad \Omega_{SDC} \approx \Omega_0 \epsilon^\lambda. \quad (17)$$

One finds from Eqs. (11) and (16) the scaling relation

$$\lambda = 2\mu + 2\nu. \quad (18)$$

In comparison, one has $\lambda = 2\mu + \nu$ in PT [14]. From Eq. (10), since J_{SDC} is positive by definition, the values of the exponents satisfy

$$\mu = 1, \quad \nu \geq 1/2, \quad \lambda = 2 + 2\nu \geq 3. \quad (19)$$

Now it is useful to further distinguish two different cases: (A1) $\nu = 1/2$ and (A2) $\nu > 1/2$. Case (A1) corresponds to a mean-field exponent ν , in which one has that

$$J_0 = \frac{2}{3} \left[1 - \frac{4\langle x^2 \rangle_x}{\xi_{2,0}^2} \right] \quad (20)$$

and

$$\Omega_0 = \frac{1}{2\sigma^2} \left[\frac{2+c^2}{\sqrt{4c^2+c^4}} - 1 \right] \frac{J_0^2}{\xi_{2,0}^2}. \quad (21)$$

The amplitudes J_0 and Ω_0 depend on two phenomenological parameters $\xi_{2,0}$ and $\langle x^2 \rangle_x$. In case (A2), the exponent ν has a non-mean-field value. Now, since $2\nu > 1$, the $\xi_2^{-2} \sim \epsilon^{2\nu}$ term in Eq. (10) only adds a correction to the leading singularity. Instead of Eq. (17), one may define

$$J_{SDC} = J_0 \epsilon^\mu [1 + j_1 \epsilon^{\mu_1} + \dots] \quad (22)$$

and

$$\Omega_{SDC} = \Omega_0 \epsilon^\lambda [1 + \omega_1 \epsilon^{\lambda_1} + \dots], \quad (23)$$

with $\mu_1 = 2\nu - \mu > 0$ and $\lambda_1 > 0$. Consequently, instead of Eq. (20), one has that

$$J_0 = 2/3, \quad j_1 = -4\langle x^2 \rangle_x / \xi_{2,0}^2. \quad (24)$$

While Ω_0 is still given by Eq. (21), one must use the corresponding new value of J_0 . The values of ω_1 and λ_1 , however, cannot be determined without knowing the behavior of ξ_2 beyond the leading term described in Eq. (16).

(B) $\tilde{\epsilon} = \epsilon - \epsilon_T$. As we mentioned, this case resembles the situation in critical phenomena in which ξ_2 diverges at ϵ_T . Then, as in critical phenomena, other quantities should also have singular behaviors at ϵ_T . Now, instead of Eq. (17) or Eqs. (22) and (23), we define, near $\tilde{\epsilon} = 0^+$, that

$$J_{SDC} \approx J_0 \epsilon - J_{s,0} \tilde{\epsilon}^\mu, \quad \Omega_{SDC} \approx \Omega_{s,0} \tilde{\epsilon}^\lambda. \quad (25)$$

The behavior of J_{SDC} is apparently dominated by the smooth background term $J_0 \epsilon$ near ϵ_T . As a consequence, the J_{SDC}^2 factor in Eq. (11) no longer contributes to the value of λ . From Eqs. (10), (11) and (16), one gets that

$$\mu = \lambda = 2\nu \quad (26)$$

instead of Eq. (19). As for the amplitudes, one finds that

$$J_0 = \frac{2}{3}, \quad J_{s,0} = \frac{8\langle x^2 \rangle_x}{3\xi_{2,0}^2}, \quad (27)$$

and

$$\Omega_{s,0} = \frac{1}{2\sigma^2} \left[\frac{2+c^2}{\sqrt{4c^2+c^4}} - 1 \right] \frac{J_0^2 \epsilon_T^2}{\xi_{2,0}^2}, \quad (28)$$

where we have used $\epsilon \approx \epsilon_T$ near $\tilde{\epsilon} = 0^+$. If 2ν is not an integer, then the best way to evaluate the exponents μ and ν is, in principle, to differentiate J_{SDC} and Ω_{SDC} with respect to ϵ and to analyze the corresponding divergences after certain orders of differentiation. The scaling relations $\mu = \lambda = 2\nu$ hence provide a very strong test for the $\tilde{\epsilon} = \epsilon - \epsilon_T$ assumption. If $\mu = 2\nu < 1$, then the slope of J_{SDC} is negative in the range of $0 < \tilde{\epsilon} < \tilde{\epsilon}_\times$ with $\tilde{\epsilon}_\times = [\mu J_{s,0} / J_0]^{1/(1-\mu)}$. The observation of a negative slope of J_{SDC} near ϵ_T will appar-

ently increase the validity of scenario (B). However, if the value of $\tilde{\epsilon}_\times$ is very small, such an observation may not be practical at present.

In critical dynamics, the correlation time as well as the correlation length exhibit similar power-law behaviors, which one would expect is also true for SDC. If so, then the correlation time τ , whose definition for SDC is given in Ref. [11], behaves like

$$\tau \approx \tau_0 \tilde{\epsilon}^{-z}, \quad (29)$$

in comparison with Eq. (16) for ξ_2 . The amplitude equation for parallel roll states predicts that $z = 2\nu = 1$. Although the values of z and ν may be different for SDC, we speculate that the scaling relation $z = 2\nu$ may still hold for SDC. Apparently, the different possible scenarios (A1), (A2), and (B) for ξ_2 are equally valid for τ . Finally, we remark that one might also expect a scaling behavior of the structure factor $S(k, \omega)$, defined for example in Ref. [11], such as

$$kS(k, \omega) = \xi_2 \mathcal{F}((k - k_{max}) \xi_2, \omega \tau). \quad (30)$$

This scaling behavior, if valid, implies Eq. (9) for the time-averaged structure factor $S(k)$ and hence is more general. We will explore this possibility elsewhere.

IV. NUMERICAL SOLUTIONS AND DATA ANALYSES

We now present our numerical studies of SDC with the GSH equations. The numerical method for solving the GSH equations is based on the work by Bjórstad *et al.* [25]. Following Ref. [7], we choose $g_m = 50$, $\sigma = 1.0$, and $c^2 = 2.0$ for parameters in Eqs. (1) and (2). In our simulation, we take a square cell of size $L_x = L_y = 128\pi$, which corresponds to an aspect ratio $\Gamma = 64$. Uniform square grids with spacing $\Delta x = \Delta y = \pi/4.0$ have been used, so the total number of nodes is 512×512 . We use the rigid boundary conditions $\psi|_B = \mathbf{n} \cdot \nabla \psi|_B = \zeta|_B = \mathbf{n} \cdot \nabla \zeta|_B = 0$ in the simulation. Here \mathbf{n} is the unit vector normal to the boundary, say B , of the domain of integration. We take two different routes to systematically study the transitions between parallel roll states and SDC states. (A) We increase the control parameter ϵ from $\epsilon = 0.05$ to $\epsilon = 0.6$ with steps of $\Delta\epsilon = 0.05$. We call this the roll branch. (B) We decrease ϵ from $\epsilon = 0.8$ to $\epsilon = 0.4$. We call this the SDC branch. For $\epsilon = 0.05$ or 0.8 , we choose initial conditions $\zeta(\mathbf{r}, t=0)$ and $\psi(\mathbf{r}, t=0)$ as random variables, obeying a Gaussian distribution with a zero mean and a variance of 0.001 . For other subsequent ϵ 's, we take the final results from the previous ϵ as our initial conditions. For each ϵ , we wait about four horizontal diffusion time t_h before collecting data that we hope is sufficient to pass the transient regime. We run for an additional $20.8t_h$ to collect 20 instantaneous profiles for SDC states or $16t_h$ to collect 10 profiles for parallel roll states during each data collection.

The patterns we observed are very similar to those found in real experiments [5,6], which can be summarized as follows. (A) Within the roll branch, straight parallel rolls are observed at $\epsilon = 0.05$ up to 0.4 with a few defects at the boundary. Starting at $\epsilon = 0.45$ up to 0.6 , the rolls start to bend and focal singularities start to appear near the boundary. A weak time dependence sets in at $\epsilon = 0.45$ in which the nucle-

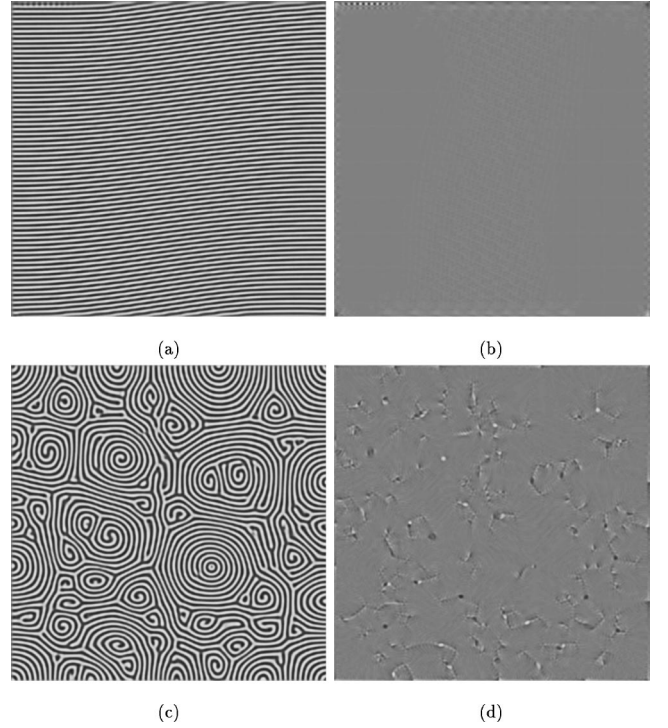


FIG. 2. Instantaneous patterns of $\psi(\mathbf{r}, t)$ and $\omega_z(\mathbf{r}, t)$. Dark regions correspond to $\psi(\mathbf{r}, t) > 0$ or $\omega_z(\mathbf{r}, t) > 0$ and white regions to $\psi(\mathbf{r}, t) < 0$ or $\omega_z(\mathbf{r}, t) < 0$. (a) $\psi(\mathbf{r}, t)$ and (b) $\omega_z(\mathbf{r}, t)$ at $\epsilon = 0.2$ on the roll branch; (c) $\psi(\mathbf{r}, t)$ and (d) $\omega_z(\mathbf{r}, t)$ at $\epsilon = 0.65$ on the SDC branch.

ation of defects along the sidewall occurs. Two typical shadow graph images, one for the order parameter $\psi(\mathbf{r}, t)$ and another for the vertical vorticity $\omega_z(\mathbf{r}, t) = -\nabla^2 \zeta(\mathbf{r}, t)$, of the roll state at $\epsilon = 0.2$ are shown in Fig. 2. (B) Within the SDC branch, SDC states are observed at $\epsilon = 0.8 - 0.55$, whose behavior has been described in detail before [5,6,15]. At $\epsilon = 0.5$, only a few spirals still exist that mix with a background of locally curved rolls. Finally, at $\epsilon = 0.4$, the pattern looks much like a roll state with a few defects and dislocations. In Fig. 2 we plot two typical shadow graph images, again one for $\psi(\mathbf{r}, t)$ and another for $\omega_z(\mathbf{r}, t)$, of SDC at $\epsilon = 0.65$. While the vertical vorticity $\omega_z(\mathbf{r})$ in a roll state is almost zero everywhere, the corresponding field has a much richer structure in SDC. This suggests choosing $\omega_z(\mathbf{r}, t)$ to be an order parameter in distinguishing a roll state from a SDC state [15]. It is interesting to point out that patterns in the interval $\epsilon = 0.4 - 0.6$ depend on their earlier histories, i.e., whether they are on the roll branch or the SDC branch; see Fig. 3. So a hysteresis loop exists when one follows the two different routes. This is consistent with experimental observations that different patterns evolve from different initial conditions at the same ϵ [12]. Owing to the existence of hysteresis, the transition temperature ϵ_T between parallel roll states and SDC states cannot be determined precisely in our study. Our rough estimate is $\epsilon_T \approx 0.45$.

In order to determine the character of the transition between rolls and SDC, we have calculated, from our numerical studies, the structure factor $S(k)$, the two-point correlation length ξ_2 , the convective current J , the vorticity current Ω , and the spectra entropy Ξ for both roll states and SDC states. The numerical methods used in calculating these

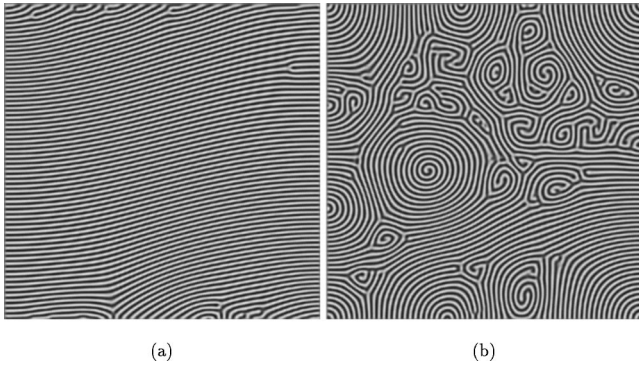


FIG. 3. Instantaneous patterns of $\psi(\mathbf{r}, t)$ at $\epsilon = 0.55$: (a) on the roll branch and (b) on the SDC branch. Dark regions correspond to $\psi(\mathbf{r}, t) > 0$ and white regions to $\psi(\mathbf{r}, t) < 0$.

quantities are the same as in Ref. [15]. The numerical uncertainties are taken as the variances of our data. Considering that we can, at most, take just a few samples of the strongly fluctuating instantaneous quantities, presumably obeying Gaussian distributions near their corresponding time-averaged values, we believe that the probabilities, and hence the uncertainties, for us to obtain the truly time-averaged values are determined by those variances. From the data for $S(k)$ of the SDC states, we have verified the existence of the scaling form (9) within our numerical uncertainties for SDC [14]. The results for ξ_2 , J , Ω , and Ξ are plotted in Figs. 4–7. The most striking feature in these figures is the hysteretic loops formed by the two branches. It is also noticeable that the uncertainties on the SDC branch are generally larger than those on the roll branch, which presumably is due to the chaotic character of SDC.

We fit the data on the roll branch with power-law behaviors. To allow for the possibility that roll states might be unstable or metastable for $\epsilon > 0.45$, only data for $0.05 \leq \epsilon \leq 0.45$ are used in actual fittings. (i) We first use the nonlinear χ^2 method to fit the convective current with $J = J_0(\epsilon - \epsilon_c)^\mu$ and find that $J_0 = 0.6554 \pm 0.0002$, $\mu = 1.0054 \pm 0.0004$, and $\epsilon_c = 0.002$. The actual accuracy in our results may not be as good as indicated. The fitting error for ϵ_c is very small. This ϵ_c is the measured onset from conduction to convection, whose positive value is most likely due to finite-size effects [26]. Apparently J on the roll branch has a mean-field exponent. The amplitude J_0 is also in good agreement with Eq. (12) provided that $\langle x^2 \rangle_x \geq 1$ is not too big. (ii) Using the χ^2 method, we fit the data for the correlation length with $\xi_2 = \xi_{2,0}(\epsilon - \epsilon_c)^{-\nu}$, which leads to $\xi_{2,0} = 13.0 \pm 0.2$ and $\nu = 0.54 \pm 0.01$. So ξ_2 on the roll branch also has a mean-field exponent. (iii) Using the χ^2 method, we fit the data for the vorticity current with $\Omega = \Omega_0(\epsilon - \epsilon_c)^\lambda$ and find that $\Omega_0 = (1.952 \pm 0.008) \times 10^{-9}$ and $\lambda = 2.461 \pm 0.003$. Again, the actual accuracy in our results may not be as good as indicated. This behavior of Ω is not easy to understand. The amplitude equations coupled with mean-flow predict, for rigid-rigid boundaries, that $\Omega \sim \epsilon^{7/2}$ for almost perfect parallel rolls and $\Omega \sim \epsilon^3$ for general patterns [18]. None of these can explain the behavior of Ω we found, which seems to be consistent with $\Omega \sim \epsilon^{5/2}$. (iv) The analysis of the spectra entropy is most difficult since there is no theory whatsoever to describe its behavior. We simply fit it to a form $\Xi = \Xi_b$

+ $\Xi_0(\epsilon - \epsilon_c)^\delta$ for the roll states. We find from the nonlinear χ^2 method that $\Xi_b = 4.24 \pm 0.04$, $\Xi_0 = 2.5 \pm 0.1$, and $\delta = 1.00 \pm 0.08$. The background term Ξ_b is much larger than the corresponding value for perfect parallel rolls $\Xi_b = \ln 2 = 0.6931$. This presumably is due to finite-size effects and/or limited computing time. The original data and their corresponding fitting curves for these global quantities are plotted in Figs. 4–7.

The analyses of the data on the SDC branch must be treated with caution given that there are three possible scaling scenarios as discussed in Sec. III. We first fit the data of ξ_2 and Ω to power laws such as (i) $\xi_2 = \xi_{2,0}(\epsilon - \epsilon_0)^{-\nu}$ and (ii) $\Omega = \Omega_0(\epsilon - \epsilon_0)^\lambda$, where $\epsilon_0 = \epsilon_c$ (the onset temperature in a finite system) in scenario (A) or $\epsilon_0 = \epsilon_T$ (the roll-to-SDC transition temperature) in scenario (B). Then we fit the data of J in accordance with our theoretical result in Eq. (10), i.e., (iii) $J = J_0(\epsilon - \epsilon_c) - J_\xi \xi_2^{-2}$, where we take the corresponding fitting results for ξ_2 in (i). Clearly the value of ϵ_0 is essential to determine which of the three scenarios is valid. In the following, we apply three different fittings for three values of ϵ_0 and check the consistency of our numerical data against the theoretical results in Eqs. (10) and (11).

(a) To check whether scenario (A), i.e., $\tilde{\epsilon} = \epsilon$, is valid, we fix $\epsilon_0 = \epsilon_c = 0.002$, whose value is given by the fitting of J on the roll branch. Since it is probable that SDC states are unstable or metastable at $\epsilon = 0.4$ and 0.45 , the corresponding data might deviate from their ‘‘real’’ values in order to form the hysteretic loops. For this reason, we disregard these two points and use only those data within $0.5 \leq \epsilon \leq 0.8$ for fitting. We use the χ^2 method to fit our data, which leads to (i) $\xi_0 = 6.8 \pm 0.2$ and $\nu = 0.72 \pm 0.05$, (ii) $\Omega_0 = (3.0 \pm 0.2) \times 10^{-8}$ and $\lambda = 3.0 \pm 0.1$, and (iii) $J_0 = 0.64 \pm 0.02$ and $J_\xi = 2.9 \pm 0.9$. The original data of ξ_2 , J , and Ω and their corresponding fitting curves are plotted in Fig. 4. Apparently those curves fit the original data well. So scenario (A) is consistent with our numerical data. To further distinguish scenario (A1) ($\nu = \frac{1}{2}$) or (A2) ($\nu > \frac{1}{2}$), we find that, on the one hand, $\nu = 0.72 \pm 0.05$ from the direct fitting in (i) but, on the other hand, $\nu = 0.50 \pm 0.05$ from $\lambda = 3.0 \pm 0.1$ in (ii) and $\lambda = 2 + 2\nu$ in Eq. (19). This discrepancy is likely caused by the big numerical uncertainties in our data. We feel that the direct fitting is more reliable and scenario (A2) is more likely to be true. However, we cannot definitely rule out scenario (A1). More accurate data are needed to resolve this issue.

(b) We check whether scenario (B), i.e., $\tilde{\epsilon} = \epsilon - \epsilon_T$, is consistent with our numerical data, where the value of ϵ_T is determined by the fitting of ξ_2 . In contrast to case (a), there is no obvious reason to disregard any point in this scenario. So all the data within $0.4 \leq \epsilon \leq 0.8$ are used in our fittings. We first use the nonlinear χ^2 method to fit the data of ξ_2 , which gives (i) $\xi_0 = 5.9 \pm 0.2$, $\nu = 0.46 \pm 0.06$, and $\epsilon_0 = \epsilon_T = 0.27 \pm 0.03$. Then we fix $\epsilon_0 = 0.27$ and use the χ^2 method to fit the data of Ω and J . We find that (ii) $\Omega_0 = (8.1 \pm 0.2) \times 10^{-8}$ and $\lambda = 2.33 \pm 0.01$ and (iii) $J_0 = 0.675 \pm 0.001$ and $J_\xi = 4.9 \pm 0.1$. These results are very sensitive to the points at $\epsilon = 0.4$ and 0.45 . The original data of ξ_2 , J , and Ω and their corresponding fitting curves are plotted in Fig. 5. The fitting of Ω obviously is not good. The results $\nu = 0.46 \pm 0.06$ in (i) and $\lambda = 2.33 \pm 0.01$ in (ii) do not satisfy the

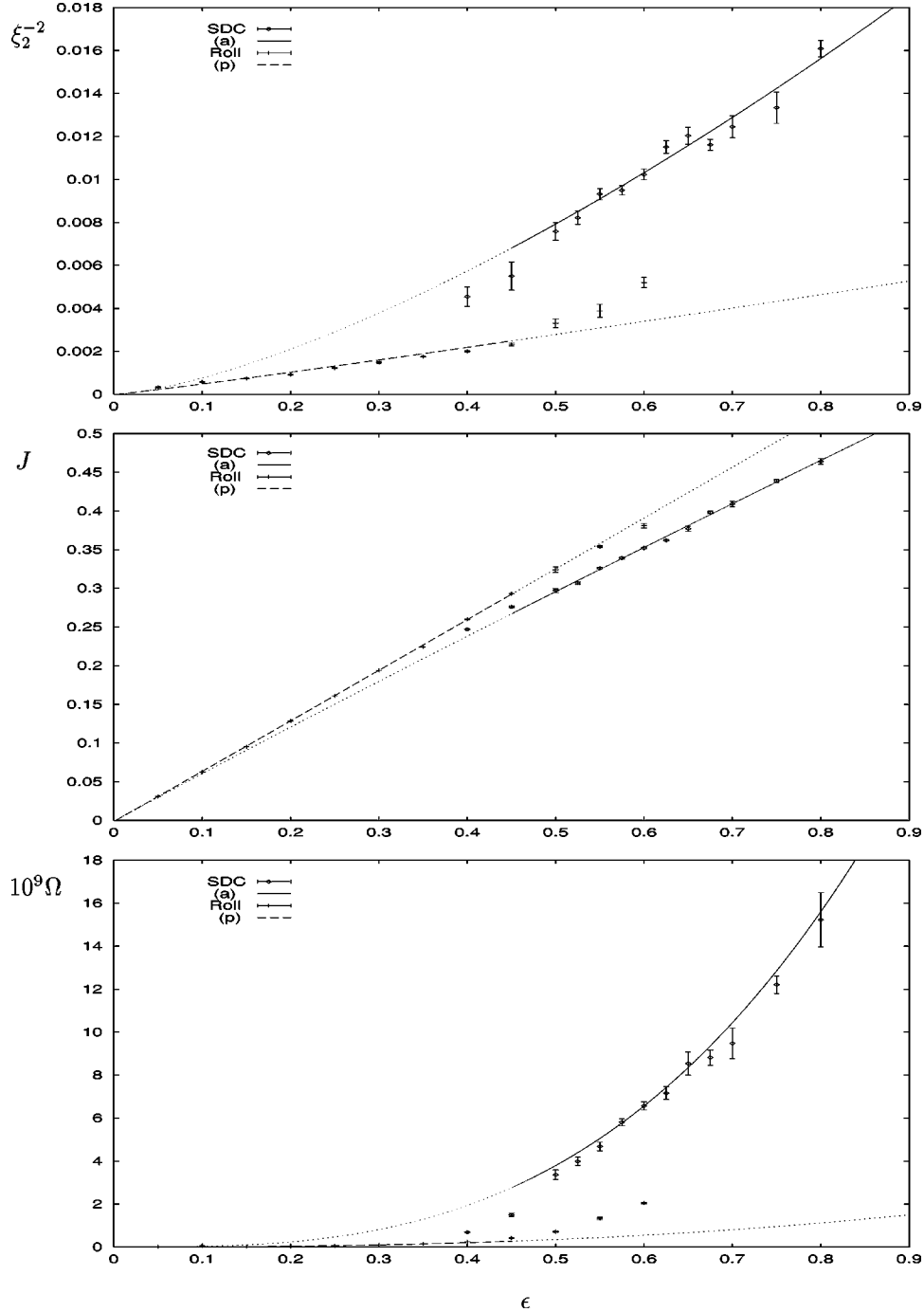


FIG. 4. Plots of ξ_2^{-2} , J , and Ω vs ϵ for both parallel rolls and SDC. The corresponding fitting curves for SDC are described in (a) in Sec. IV. The following labels are used: SDC, the numerical data with error bars on the SDC branch; (a), the fitting curves for SDC described in (a) in the text; Roll, the numerical data with error bars on the roll branch; (p), the fitting curves for parallel rolls. To indicate that the parallel roll states for $\epsilon > \epsilon_T$ and the SDC states for $\epsilon < \epsilon_T$ may be metastable, the corresponding fitting curves for (a) and (p) are plotted with dotted lines. The transition temperature is estimated roughly at $\epsilon_T = 0.45$.

scaling relation $\lambda = 2\nu$ in Eq. (26). So scenario (B) with $\epsilon_T = 0.27$ is unlikely to be true.

(c) We check whether scenario (B), with ϵ_T determined by the fitting of Ω , is consistent with our numerical data. As in case (b), we use all the data within $0.4 \leq \epsilon \leq 0.8$ in our fittings. We first use the nonlinear χ^2 method to fit the data of Ω and find that (ii) $\Omega_0 = (4.5 \pm 0.3) \times 10^{-8}$, $\lambda = 1.41 \pm 0.07$, and $\epsilon_T = 0.348 \pm 0.005$. Then we fix $\epsilon_0 = 0.348$ and apply the χ^2 method to fit the data of ξ_2 and J . We find that

(i) $\xi_{2,0} = 6.55 \pm 0.09$ and $\nu = 0.295 \pm 0.008$, and (iii) $J_0 = 0.667 \pm 0.001$ and $J_\xi = 4.6 \pm 0.1$. Again, these fitting results are very sensitive to the points at $\epsilon = 0.4$ and 0.45 . The original data of ξ_2 , J , and Ω and their corresponding fitting curves are plotted in Fig. 6. Notice that since ν in (i) is less than $\frac{1}{2}$, the slope of J is negative in the range of $0 < \tilde{\epsilon} = \epsilon - \epsilon_T < \tilde{\epsilon}_\times$ with $\tilde{\epsilon}_\times = [2\nu J_\xi / \xi_{2,0}^2 J_0]^{1/(1-2\nu)}$. In the present case, one has $\tilde{\epsilon}_\times = 3.20 \times 10^{-3}$, which perhaps is too small

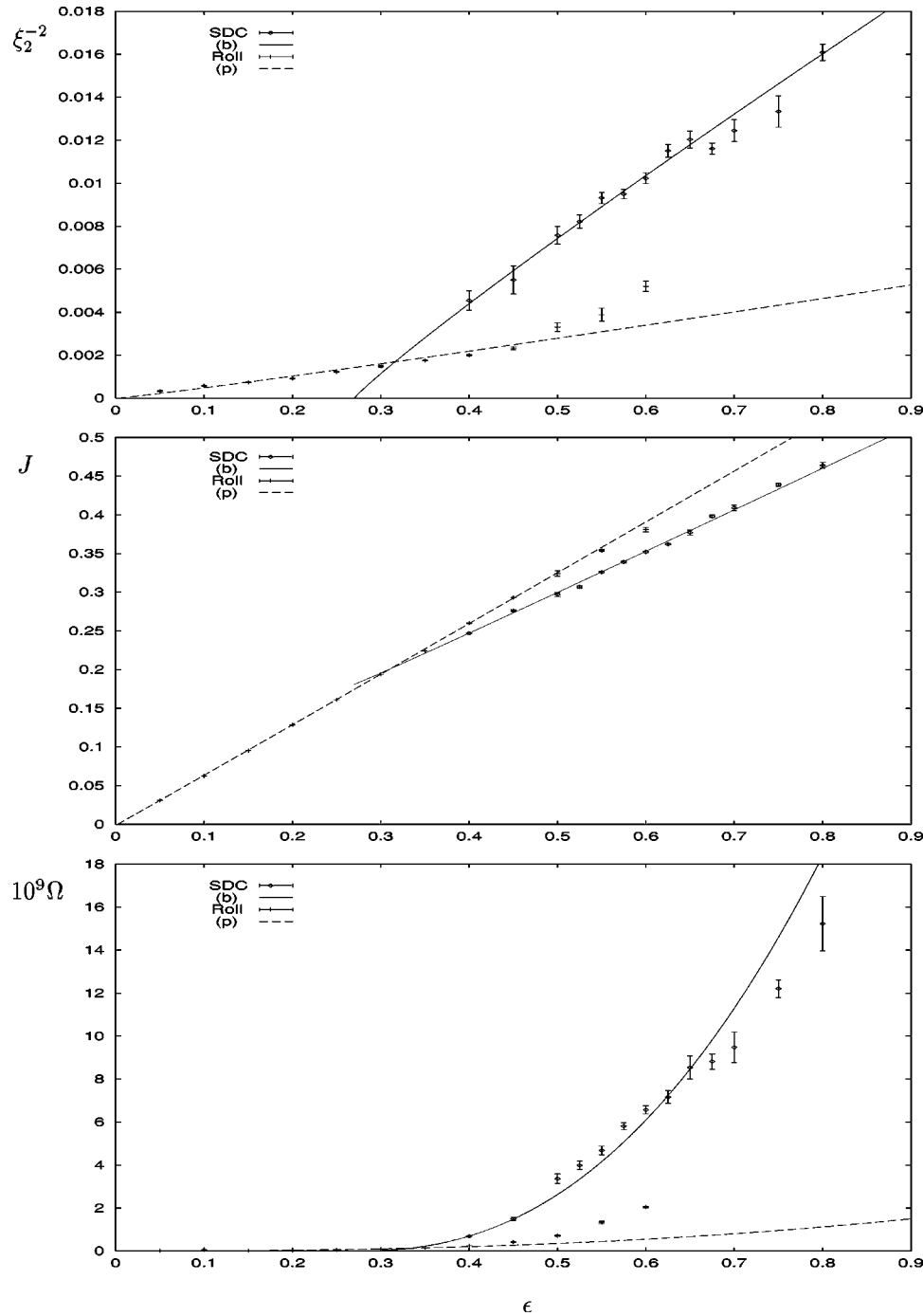


FIG. 5. Plots of ξ_2^{-2} , J , and Ω vs ϵ for both parallel rolls and SDC. The corresponding fitting curves for SDC are described in (b) in Sec. IV. The following labels are used: SDC, the numerical data with error bars on the SDC branch; (b), the fitting curves for SDC described in (b) in the text; Roll, the numerical data with error bars on the roll branch; (p), the fitting curves for parallel rolls.

to be checked by real experiments or simulations. From the pure-data-fitting point of view, the fittings in this case are as good as the fittings in case (a). So, without the benefit of our theoretical results, scenario (B) with $\epsilon_T=0.348$ could be (incorrectly) accepted. However, the exponents $\nu=0.295 \pm 0.008$ in (i) and $\lambda=1.41 \pm 0.07$ in (ii) are not even close to satisfying the scaling relation $\lambda=2\nu$ in Eq. (26). So this scenario can be ruled out by our theory. From this, together with the discussions in cases (a) and (b), we conclude that scenario (B) is unlikely to be valid for SDC and scenario (A) is consistent with our numerical data and our theory.

It is worthwhile to mention that, in all cases above, the value of J_0 agrees with the theoretical result $2/3$ in Eq. (10); the value of J_ξ is also consistent with the theoretical prediction $J_\xi \geq 8/3$. On the other hand, the theoretical results in Eqs. (21) and (28) predict that $\Omega_0=7.4 \times 10^{-4}$ in case (a), $\Omega_0=7.2 \times 10^{-5}$ in case (b), and $\Omega_0=9.7 \times 10^{-5}$ in case (c). All these predictions are several orders larger than the corresponding numerical results. The reason for such big discrepancies is not clear to us.

We have also studied the behavior of the spectra entropy. Owing to the lack of any theory, we simply fit the data of Ξ

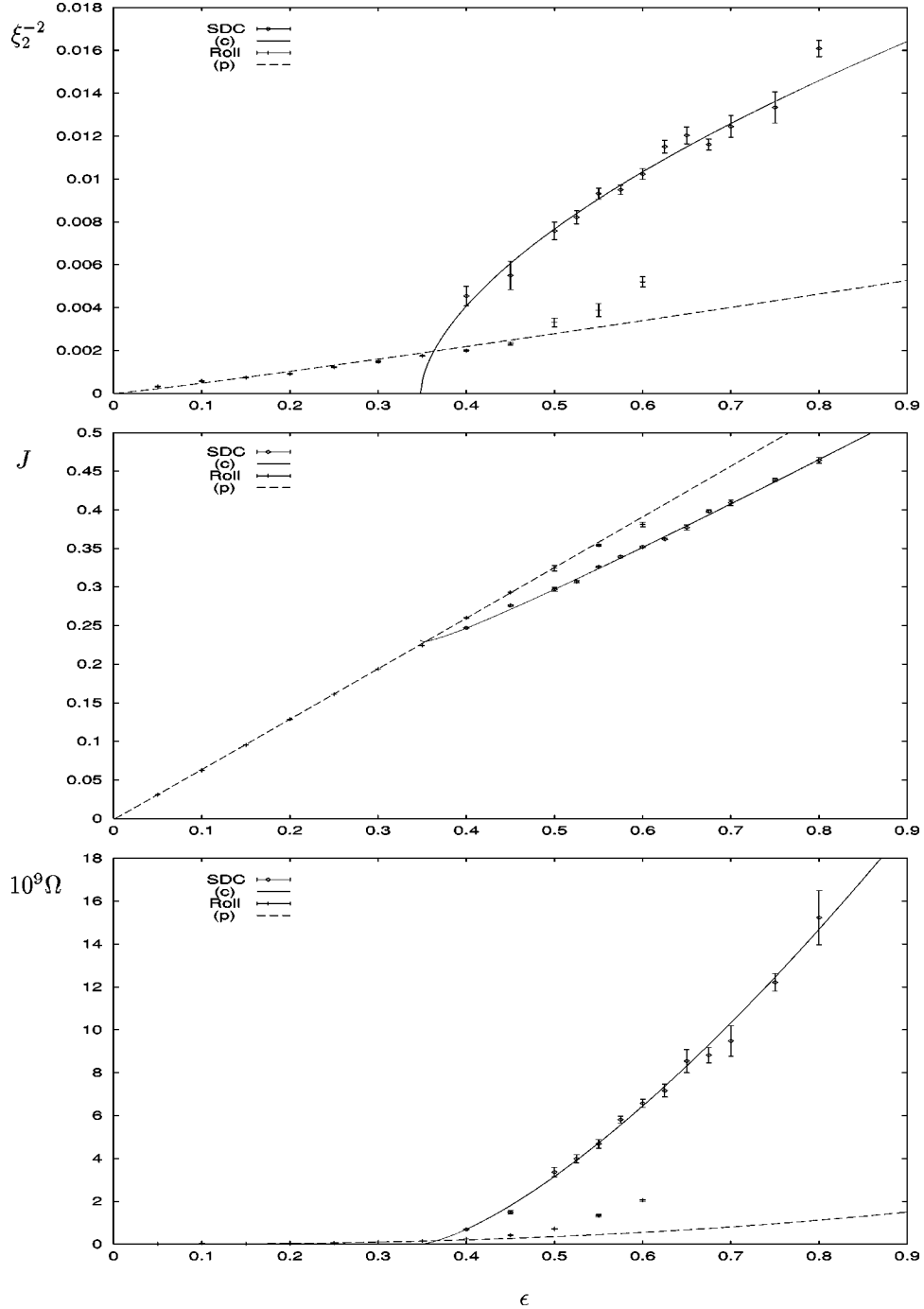


FIG. 6. Plots of ξ_2^{-2} , J , and Ω vs ϵ for both parallel rolls and SDC. The corresponding fitting curves for SDC are described in (c) in Sec. IV. The following labels are used: SDC, the numerical data with error bars on the SDC branch; (c), the fitting curves for SDC described in (c) in the text; Roll, the numerical data with error bars on the roll branch; (p), the fitting curves for parallel rolls.

to a form $\Xi = \Xi_b + \Xi_0(\epsilon - \epsilon_0)^\delta$ for the SDC branch. We apply two different fittings. (a) We fix $\epsilon_0 = \epsilon_c$ and $\Xi_b = 4.24$ (from the fitting for the roll branch) and use the χ^2 method to fit those data within $0.5 \leq \epsilon \leq 0.8$, which leads to $\Xi_0 = 4.79 \pm 0.03$ and $\delta = 0.18 \pm 0.02$. (b) We fix $\Xi_b = 4.24$ and use the nonlinear χ^2 method for all data within $0.4 \leq \epsilon \leq 0.8$, which gives that $\Xi_0 = 5.13 \pm 0.05$, $\delta = 0.12 \pm 0.01$, and $\epsilon_0 = 0.37 \pm 0.02$. We have also tried other alternative fittings such as using the nonlinear χ^2 method for all data within $0.4 \leq \epsilon \leq 0.8$ and fixing $\epsilon_0 = 0.27$ [from (i) in (b)] or $\epsilon_0 = 0.348$ [from (ii) in (c)], but none of them gives a reason-

able fit. The fitting curves in (a) and (b) and the original data of Ξ are plotted in Fig. 7. At this stage, the behavior of Ξ is the most unclear one among all the time-averaged global quantities defined in Sec. II.

V. DISCUSSION AND CONCLUSION

In the preceding section we concluded that scenario (A) is valid for SDC. This means that ξ_2 diverges at $\epsilon = 0$ and J and Ω vanish at $\epsilon = 0$. At first sight it seems puzzling that all properties of SDC are controlled by ϵ , instead of $\epsilon - \epsilon_T$. To

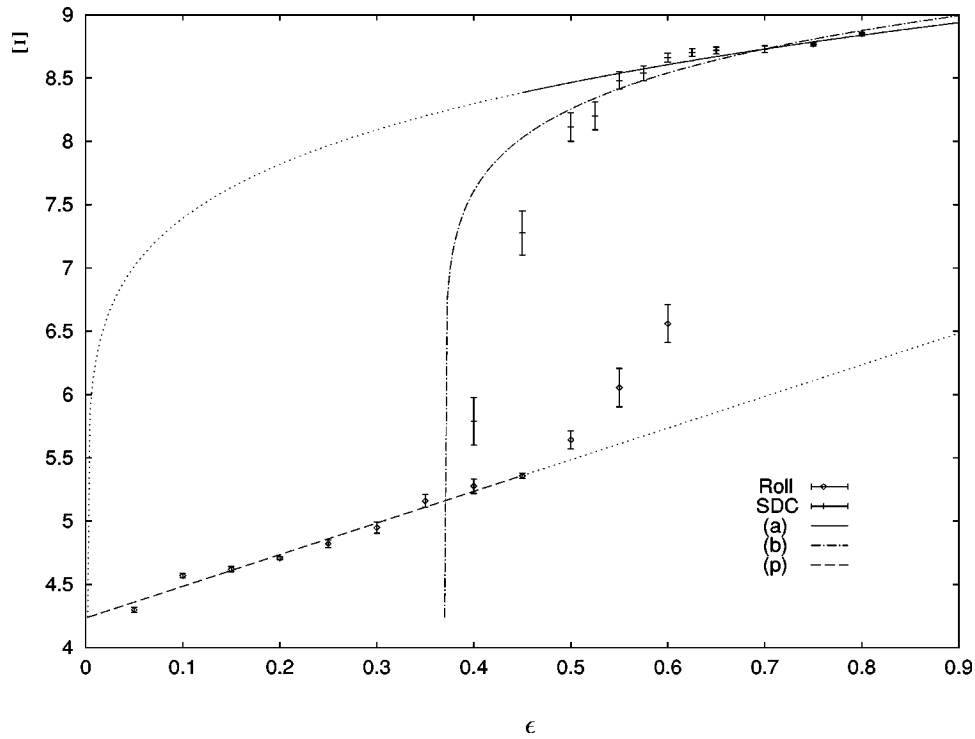


FIG. 7. Plot of Ξ vs ϵ for both parallel rolls and SDC. The different fitting forms (a) and (b) for SDC are discussed in the text. The following labels are used: Roll, the numerical data with error bars on the roll branch; SDC, the numerical data with error bars on the SDC branch; (a), the fitting curve for SDC described in (a) in the text; (b), the fitting curve for SDC described in (b) in the text; (p), the fitting curve for parallel rolls. To indicate that the parallel roll states for $\epsilon > \epsilon_T$ and the SDC states for $\epsilon < \epsilon_T$ may be metastable, the corresponding fitting curves in (a) and (p) are plotted with dotted lines. The transition temperature is estimated roughly at $\epsilon_T = 0.45$.

understand this, we propose an explanation for this scenario, which is somewhat similar to that in the hexagon-to-roll transition in non-Boussinesq fluids [20]. In the latter case, the transition from hexagonal states to parallel roll states occurs at finite ϵ_T . Although the roll attractor is unstable for small enough ϵ and metastable against the hexagonal attractor for even slightly larger ϵ , the properties of the parallel roll states are all controlled by ϵ , not by $\epsilon - \epsilon_T$ [20]. Clearly, one can imagine a similar picture for the roll-to-SDC transition. While the SDC attractor seems to be either unstable or metastable against the roll attractor for sufficiently small ϵ , as an intrinsic convective state, the properties of SDC are controlled at the conduction to convection threshold, not where it starts to emerge as the stable state. The existence of two different attractors has been suggested by experiments [11,12]. The basins and the stability of these two attractors are still unclear at present.

The establishment of scenario (A) indicates that the transition between the parallel roll states and the SDC states is first order. This conclusion is also supported by the following.

(1) Our theory predicts discontinuities in the value and the slope of J at ϵ_T [see the discussion following Eq. (15)]. This is a typical signature of a first-order transition.

(2) The presence of hysteresis loops in Figs. 4–7 is a strong indication of a first-order transition. A different hysteresis loop has also been reported by others for the GSH model [13]. Although it is arguable that hysteresis loops may be found in a second-order transition if the computing time is not long enough to overcome the effects of critical slowing

down (which occurs when the correlation time τ approaches infinity), it is doubtful that the loops in that case can be as distinctive as what we found in Figs. 4–7.

(3) As we described in Sec. IV, the convective patterns depend on the processes leading to them, which is also observed in experiments [12]. This fact suggests that the two competing attractors are either both stable or one is stable while the other is metastable for some positive ϵ . Such a stability property is typical in first-order transitions. On the contrary, in second-order transitions one of the two attractors should change from stable to unstable while the other changes from unstable to stable as ϵ moves across ϵ_T .

(4) From Figs. 5–7 it is easy to see that if scenario (B) is valid, then the fitting curves of all the time-averaged global quantities on the SDC branch will cross those on the roll branch. But there is no evidence from our numerical calculation supporting such a crossing.

As we mentioned in Sec. I, an earlier experiment with a circular cell [11] found that ξ_2 diverges at $\epsilon = 0$ with a mean-field exponent, while the correlation time τ either diverges at $\epsilon = 0$ with a non-mean-field exponent or diverges at the roll-to-SDC transition temperature ϵ_T with a mean-field exponent. However, a recent experiment with a square cell [12] concluded that ξ_2 diverges at ϵ_T with a very small exponent ν . We now comment on these experiments and our study.

Regarding our numerical study, we cannot rule out that the roll-to-SDC transition in the GSH model has a different character from those in real experiments, although this seems unlikely. We also cannot rule out that our numerical solutions are still in the transient regime even though we have

waited for about four horizontal diffusion times t_h before collecting data over an interval of several t_h for each ϵ . Furthermore, as we discussed in Sec. IV, our numerical data are not accurate enough to determine independently which of the three scenarios is true for SDC. As a result, we have to rely on our theoretical predictions to resolve this issue. Finally, we disregarded two data points in our analysis for scenario (A) on the basis that these two points deviate from their ‘‘real’’ values to form hysteretic loops. This introduces a certain arbitrariness in determining which data points deviate. These shortcomings in our numerical study weaken the validity of our conclusion.

We notice that the data of the correlation length ξ_2 for parallel rolls and SDC were analyzed together in the experiment by Morris *et al.* [11], which we think is not justified. Considering that the parallel roll states and the SDC states are intrinsically different, we believe it is necessary to separate their data in the analysis, such as we did in Sec. IV. Such a separation was implicit for the data of the correlation time τ since $\tau = +\infty$ for steady states such as parallel rolls and, in principle, only the data for SDC are available. A divergence at $\epsilon = 0$ with a non-mean-field exponent was found to be consistent with the data of τ for SDC [11]. It is not clear to us whether a similar conclusion can be reached for ξ_2 if its data for SDC are analyzed separately.

In a recent interesting experiment, Cakmur *et al.* [12] were able to observe the ideal parallel roll state predicted by theory by a tilting of a square convection cell. They were able to demonstrate that there was a range of the control parameter in which the SDC and parallel roll states were bistable. Indeed, the qualitative features are quite similar to those observed in our numerical simulation, except that they were also able to observe oscillatory parallel roll and SDC states. They characterized the transition between the parallel roll and SDC states using the spatial correlation length and the spectral entropy and concluded that ξ_2 diverges at ϵ_T with a small exponent ν , consistent with a second-order transition. They also observed, however, that the parallel roll state and the SDC state competed with each other via a front propagation, which, together with the bistability, suggests a first-order transition, and concluded that further studies were necessary to elucidate the true nature of the transition. Their analysis of ξ_2 is in fact essentially our scenario (B), which we have argued is unlikely to be the case. We would also note that to convincingly show that ξ_2 for SDC diverges at ϵ_T , one must have a sufficient number of data points whose ξ_2 are much *larger* than the corresponding typical values of parallel rolls (for ϵ away from both 0 and ϵ_T). Otherwise the

data for ξ_2 for SDC may simply approach those for parallel rolls to form a hysteretic loop near ϵ_T , instead of diverging at ϵ_T .

As we discussed in Sec. IV, our theory plays an important role in determining the nature of the roll-to-SDC transition. So it is very important to check our theoretical predictions by real experiments. One important prediction by our theory is that there exist discontinuities in the value and the slope of J at ϵ_T . However, we realize that no discontinuity in J has been reported by experiments. The reason for this is not clear to us. We conjecture that finite-size effects might play a role. From Fig. 1 we find that the discontinuity is larger for smaller Prandtl number σ . So it would be interesting to see whether experiments can confirm or rule out such a discontinuity in J by using a small σ . Another important prediction from our analysis is the behavior of the time-averaged vorticity current Ω . Since direct measurements of Ω seem to be very difficult in real experiments [27], we think it valuable to *calculate* Ω by solving Eq. (2) (the corresponding version before rescalings can be found in Ref. [14]) or its improved versions numerically, with the experimental results of $\psi(\mathbf{r}, t)$ as input. Such a calculation will not only help to clarify the nature of the roll-to-SDC transition, but also provide an additional experimental test on our theory [14]. It would also be useful to calculate the time-averaged spectra entropy as suggested in Refs. [12,15], even though there is no theory to predict the behavior of this quantity.

In summary, we conclude from our numerical studies and our theoretical results that the roll-to-SDC transition is first order in character. We found that the correlation length ξ_2 for SDC diverges at $\epsilon = 0$, not at the transition temperature ϵ_T . However, since the uncertainties in our data are unpleasantly large and the data points we have are unsatisfactorily few in number, we cannot determine definitely whether or not the exponent of ξ_2 is mean field. So further investigations are necessary to draw a definite conclusion. In this regard, a theoretical calculation of ξ_2 for SDC is highly desirable. A theory to describe the roll-to-SDC transition is essential. Finite-size effects should also be studied carefully.

ACKNOWLEDGMENT

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