II. Hardness and Indentation Behavior

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Fracture mostly initiates at the surface of glass structures



Understanding surface damage is a key issue in glass science





Vision au travers d'un pare-brise usé. Phénomène de diffraction. Piéton non visible



Vision au travers d'un pare-brise non usé. Image claire. Piéton visible

Surface damage alters

- The strength
- The visual aspect (aesthetics)
- The function



The Indentation Deformation Process





Hardness: « Like the storming of the seas, is easily appreciated but not readily measured » (O' Neill, 1934)

Several definitions:

Resistance to deformation under sharp contact loading
 H_{steel} > H_{rubber}

• Resistance to permanent deformation *H_{rubber} > H_{steel}*

In contrast with metals, for which hardness is mainly related to plastic flow, polymers and glasses behave elastic to a great extent



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Indentation mechanics

I. Rheology

I.1. The stress (available macrscopic parameter)

• σ=P/contact surface: Vickers hardness (Hv=1,8544M/d², M: kg, d=2a: mm)

• σ=P/projected contact surface: Meyer's hardness (Meyer, 1908)



P=kaⁿ (Meyer's law) n∈[1-2] dH/dP≤0 !



I.2. Strain

Preliminary remarks:

Small strain hypothesis: $\epsilon_{ij}=1/2(u_{i,j}+u_{ji})$ (= (1-1₀)/1₀ in uniaxial loading)

For large strains: $d\epsilon = dl/l$ et $\epsilon = ln (l/l_0)$ (100% in tension -50% in compression)

• For a ball on plane problem, $\varepsilon \approx 0.2a/R$ (R: indenter radius) (Tabor, 1950)

• General case: $d\epsilon = \beta du/u$, with $\beta = \cot \psi$ (Sakai, 1999)

dε=β du/u NB: u=γu_c=γa/tan ψ With γ∈[1- $\pi/2$] = $\pi/2$ in pure elasticity for a conical indenter (Love, 1939)



I.3. Constitutive law

Elasticity

Local description:

Contact loading (Boussinesq, 1885) + Blister field (Yoffe, 1982) E. H. Yoffe

Effect of blister field on a hemispherical cavity; shear stress τ and normal stress σ_r are indicated by the arrows.

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Mean stress value:

 $\sigma = \gamma^2 / (2u^2 tan^2 \psi) P$ (Vickers) Et d $\epsilon = \beta$ du/u

E=2(1- v^2) tan $\psi \sigma$ (or contact hardness) (Stillwell – Tabor, 1961)

P=E tan $\psi/[(1-v^2)\gamma^2]u_e^2$

NB:where ψ is an equivalent cone angle: $\pi a^2 = 2a_v^2$ ($\psi = 70.3^\circ$) (cone) (Vickers)

a – The elastic contribution

Elastic recovery

-- Indenter position at maximum penetration depth



 $E=P(1-v^2)\gamma^2/(\sqrt{2\pi} \tan \psi uu_e)$ (Sneddon, 1965 - Loubet, 1986) ¹⁰

I.3. Constitutive law

Plasticity

σ (=P/(2a²)) = χY with χ∈[3-3,5] (Ishlinsky, 1944)

 $P=(2\beta Ytan^2\psi/\gamma^2)u_p^2$

Elasto-Plasticity

 $u=u_e+u_p$ $P=K_{ep}u^2$ With $K_{ep}=[(K_e)^{-1/2}+(K_p)^{-1/2}]^{-2}$

P= $\sqrt{2\pi}$ E tanψ/((1-ν²)γ²)uu_e (Sneddon, 1965 -Loubet, 1986) P=E tanψ/((1-ν²)γ²)(2u-u_e)u_e (Lawn, 1981)

NB: The elastic recovery oes not affect the hardness measurement



I.3. Constitutive laws

Viscosity

Recall:

 $\sigma_{ij} = (-p + \lambda d\epsilon_{kk}/dt)\delta_{ij} + 2\eta d\epsilon_{ij}/dt$ (Newtonian viscosity)

η: dynamical viscosity coefficient (Pa.s)

Stokes law (1885): P=6 η Rdu/dt (sphere with radius R in a viscous fluid)) For a cone: P α η udu/dt (α : proportionnal) u² α P/ η t And H α P/u² H α η /t

H=4 η /(π t tan ψ) (Yang, 1997)

Elasticity (Hooke) - Viscosity (Newton) analogy: $H=\eta/((1-v)t \tan \psi)$ (Sakai, 1999)

Non-linear viscosity: $d\epsilon/dt \alpha \sigma^n \equiv \alpha (d\epsilon/dt)^{(1-n)/n}$ and $H \alpha t^{-1/n} exp[\Delta G_a/(nRT)]$ (Guin, 2002)



I.3. Constitutive laws

Viscoelasticity

Using known elastcity solution transposed to pure Newtonian viscosity problems by means of the Boltzmann superposition principle (Lee & Radok, 1960) (Ting, 1966) (Shimizu, 1999)

 $\begin{array}{l} H=1/[2tan\psi~(1-\nu^2)J(t)]\\ \textbf{Constant load, with }J(t)=\epsilon(t)/\sigma_o\text{: creep}\\ \textbf{compliance} \end{array}$

 $\begin{array}{l} H=G(t)/[2tan\psi~(1-\nu^2)] \\ \mbox{For imposed constant displacement, where} \\ G(t)=\sigma(t)/\epsilon_o: \mbox{ relaxation modulus} \end{array}$



Schematic setup for constant-load creep test.

Indentation creep



II.2 Critical load for cracking

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Indentation=flaw

K_{lc} \alpha \sigma \sqrt{a}

P_c \alpha \sigma a^2 \alpha K_{lc} a^{3/2}

\sigma \alpha P/a^2
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P_{c} = K_{lc}(\pi a)^{3/2} tan\psi (Lawn, 1975)
Typically: \psi = 68^{\circ}, K_{lc} = 1 MPa and H=5 GPa \implies a = 2 \mu m
With H=P/(2a<sup>2</sup>), one obtains:
P_{c} = 2.2.10^{4} K_{lc}^{4}/H^{3} (Lawn, 1977)
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P_c = 885 K_{Ic}⁴/H³ (Hagan, 1979)



- Simulation of the Vickers indentation (F=100 mN)

High pressure set-up

T = 293 K $P = 3 \sim 25 GPa$ $t = 1 \sim 720 min$

Multi-anvil press













The Densification contribution



H. Ji, V. Keryvin, T. Rouxel and T. Hammouda, Scripta Mat., 55 1159-1162 (2006).

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Quantitative evaluation of the amount of densification

Bi-refringence effects (Ernsberger (1968), Peter (1970), Arora (1979))

Deformation recovery after annealing (Neely (1968), Yoshida (2001))

(Neely and Mackenzie, 1968)



The Densification contribution: experimental evidence from Vickers indentation

Load must be lower than 50 g







Plasticine as a model material

The two different mechanisms:

77 K

Densification: Low temperature High T_g glasses Low Poisson's ratio glasses

293 K

Volume conservative shear flow: High temperature $(\geq T_g)$ Low T_g glasses High Poisson's ratio glasses

Conclusion 2: INDENTATION BEHAVIOR

1) Densification can represent up to 90% of the indentation volume in silica and 80% in window glass but is almost neligible in ZrCuAlNi BMG

2) The shear-flow contribution increases with respect to the densification one as temperature increases

3) One can have an idea of the predominant indentation deformation mechanism and indentation cracking resistance from the value of Poisson's ratio

