## ME 350/450: ADVANCED TOPICS IN CONTROLS CONTROL OF PARTIAL DIFFERENTIAL EQUATION (PDE) SYSTEMS

http://www.lehigh.edu/~eus204/teaching/ME450\_CDPS/ME450\_CDPS.html

Instructor: Eugenio Schuster Room 454, Packard Laboratory Phone: (610) 758-5253 Email: schuster@lehigh.edu

Class Times Tue/Th 4:25 - 5:40PM

**Location** Remote

Course Introduction to partial differential equation (PDE) systems and their control.

Description: Lyapunov stability analysis for PDE systems. Backstepping control. Model

Reduction. Boundary control of parabolic and hyperbolic PDE's. Interior

control of parabolic and hyperbolic PDE's.

Textbook: "Nonlinear and Robust Control of PDE Systems", by Panagiotis D.

Christofides, Birkhauser 2001. ISBN: 0-8176-4156-4.

"Boundary Control of PDEs: A Course on Backstepping Designs" by Miroslav Krstic and Andrey Smyshlyaev, SIAM 2008, ISBN: 978-0898716-

50-4.

"Nonlinear Systems", by Hassan K. Khalil, Third Edition, Prentice Hall

2002, ISBN: 0-1306-7389-7.

**Prerequisites**: ME 343, ME 433, ME 450 (Nonlinear Systems) or consent of the instructor.

Office Hours: After class or by appointment

Syllabus: - Stability: Direct and converse Lyapunov theorems, Lasalle's theorem

- Backstepping Control

- Introduction to Partial Differential Equations

- Model Reduction

Boundary Control of PDE'sInterior Control of PDE'sDiffusivity Control of PDE's