

ME242 – MECHANICAL ENGINEERING SYSTEMS

LECTURE 34:

- Over-casual and Under-casual Systems 5.1

UNDER-CASUAL SYSTEMS

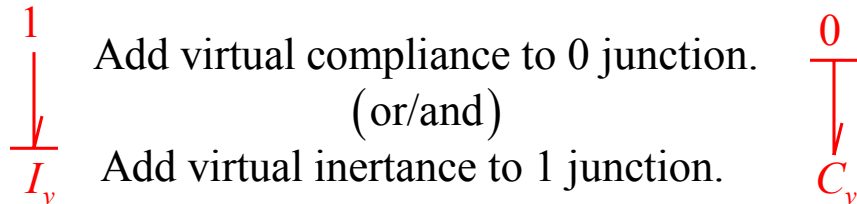
Causality insufficient to define all efforts and flows.

Virtual compliances or/and inertances needed.

Using bond graphs produces some algebraic equations.

UNDER-CASUAL SYSTEMS

Standard procedure leaves bonds with no strokes.



Add virtual compliance to 0 junction.
(or/and)

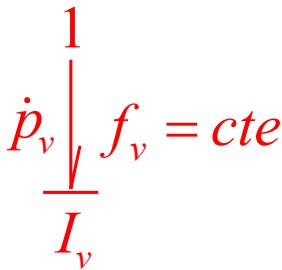
Add virtual inertance to 1 junction.

These elements have zero moduli ($C_v = 0, I_v = 0$)

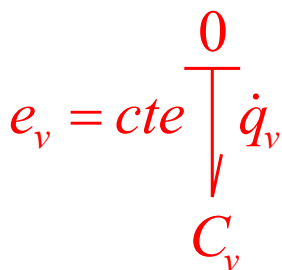
and zero initial state. ($q_v = 0, p_v = 0$)

This is the "algebraic-reduction method"

UNDER-CASUAL SYSTEMS



$$p_v = I_v f_v = 0 \Rightarrow \dot{p}_v = 0$$



$$q_v = C_v e_v = 0 \Rightarrow \dot{q}_v = 0$$

UNDER-CASUAL SYSTEMS

Application of the method results in

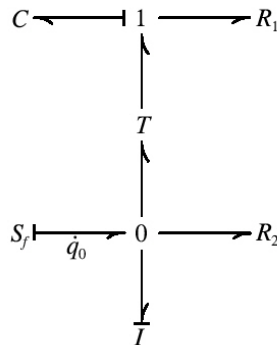
Semi-Explicit Form

$$\frac{d\mathbf{x}}{dt} = \mathbf{f}(\mathbf{x}, \mathbf{u}, t)$$

$$\mathbf{0} = \mathbf{g}(\mathbf{x}, \mathbf{u}, t)$$

UNDER-CASUAL SYSTEMS

Case Study:

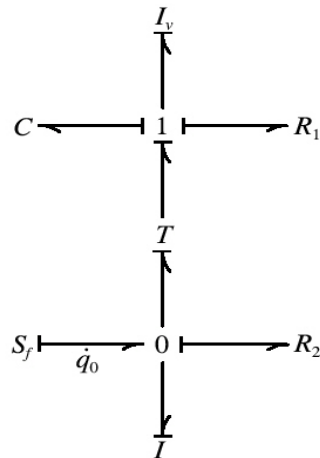


Is this under-casual?

(a) steps 1-4 for placing causal strokes

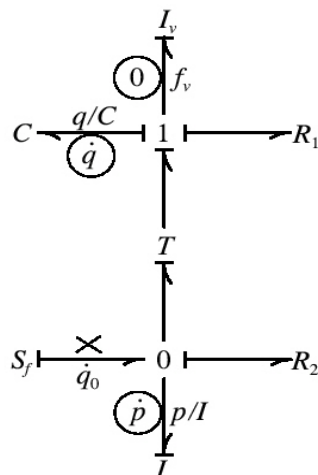
Where can we place virtual storage devices?

UNDER-CASUAL SYSTEMS



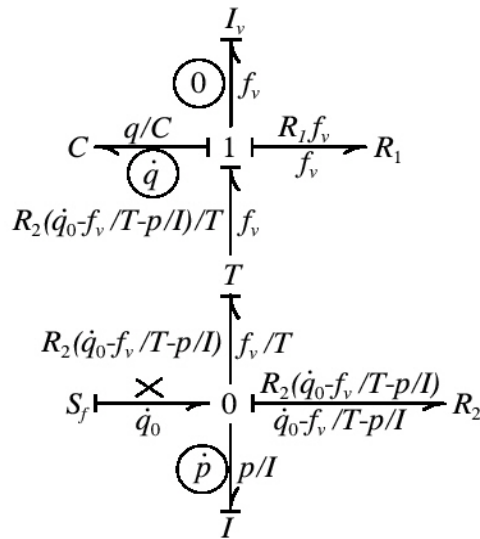
(b) step 5 with virtual inertance

UNDER-CASUAL SYSTEMS



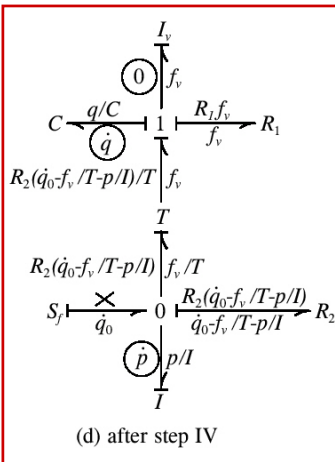
(c) steps I-II of procedure to write the differential equations

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(d) after step IV

UNDER-CASUAL SYSTEMS



(d) after step IV

$$\frac{dq}{dt} = f_v$$

$$\frac{dp}{dt} = R_2 \left(\dot{q}_0 - \frac{f_v}{T} - \frac{p}{I} \right)$$

$$0 = \frac{R_2}{T} \left(\dot{q}_0 - \frac{f_v}{T} - \frac{p}{I} \right) - \frac{q}{C} - R_1 f_v$$

UNDER-CASUAL SYSTEMS

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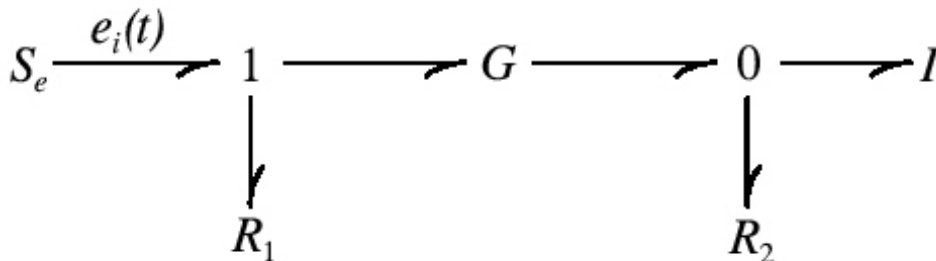


$$\frac{dq}{dt} = \frac{T}{1 + R_1 T^2 / R_2} \left[\dot{q}_0 - \frac{1}{I} p - \frac{T}{R_1 C} q \right],$$

$$\frac{dp}{dt} = \frac{T}{1 + R_1 T^2 / R_2} \left[R_1 T \dot{q}_0 - \frac{R_1 T}{I} p + \frac{1}{C} q \right]$$

UNDER-CASUAL SYSTEMS

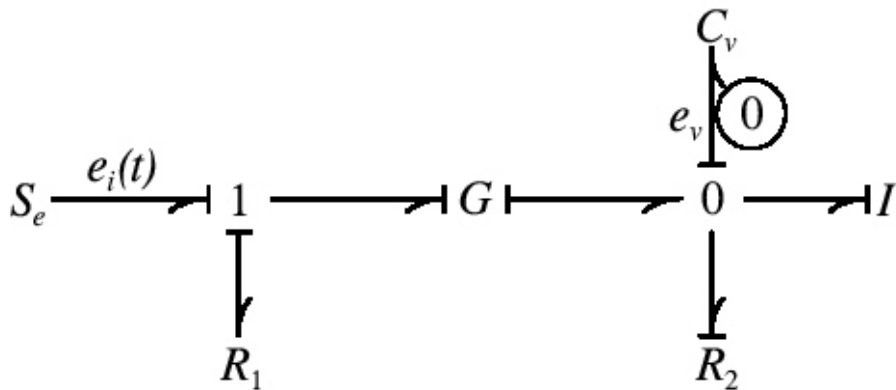
Example:



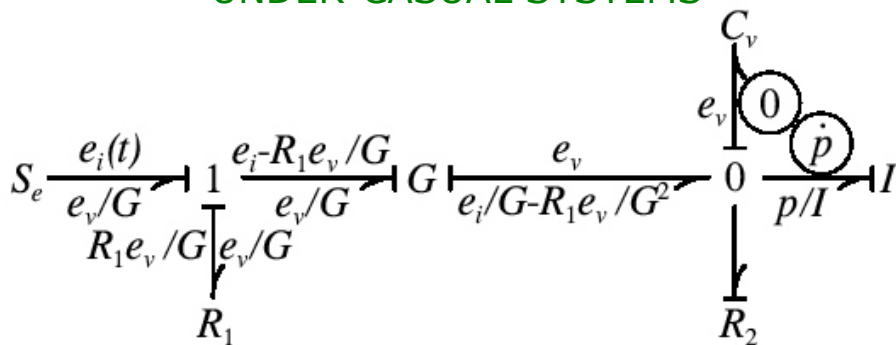
Is this under-casual?

Where can we place virtual storage devices?

UNDER-CASUAL SYSTEMS



UNDER-CASUAL SYSTEMS



$$\frac{dp}{dt} = e_v = \frac{1}{R_1/G^2 - 1/R_2} \left(\frac{1}{G} e_i(t) - \frac{1}{I} p \right)$$