

LINEAR ALGEBRA VI - LINEAR MODELS AND DECISIONS

LINEAR TRANSFORMATIONS

$L: V \rightarrow V$ IS A LINEAR TRANSFORMATION ON V IFF $L(\alpha_1 v_1 + \dots + \alpha_n v_n) = \alpha_1 L(v_1) + \dots + \alpha_n L(v_n)$

$\therefore L(v) = L\left(\begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix}\right) = L(\alpha_1 v_1 + \dots + \alpha_n v_n)$ [FOR $\langle v_1, \dots, v_n \rangle$ A BASIS] $= \alpha_1 L(v_1) + \dots + \alpha_n L(v_n)$

THUS ANY TRANSFORMATION IS COMPLETELY SPECIFIED BY WHAT IT DOES TO THE BASIS VECTORS

FOR v_i A BASIS VECTOR, $L(v_i) = m_{i1} v_1 + \dots + m_{in} v_n$, A LINEAR COMBINATION OF THE BASIS VECTORS

THAT IS, $L(v_i) = \begin{pmatrix} m_{i1} \\ \vdots \\ m_{in} \end{pmatrix}$

THUS, $\{L(v_1) \dots L(v_n)\} = \left\{ \begin{pmatrix} m_{11} \\ \vdots \\ m_{n1} \end{pmatrix} \dots \begin{pmatrix} m_{1n} \\ \vdots \\ m_{nn} \end{pmatrix} \right\} = \begin{pmatrix} m_{11} & m_{12} & \dots & m_{1n} \\ m_{21} & m_{22} & \dots & m_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ m_{n1} & m_{n2} & \dots & m_{nn} \end{pmatrix}$

COMPLETELY SPECIFIES THE LINEAR TRANSFORMATION L

FURTHERMORE,

$$L(v) = L\left(\begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix}\right) = \alpha_1 L(v_1) + \dots + \alpha_n L(v_n) = \begin{pmatrix} m_{11} & \dots & m_{1n} \\ \vdots & \ddots & \vdots \\ m_{n1} & \dots & m_{nn} \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix} = \alpha_1 \begin{pmatrix} m_{11} \\ \vdots \\ m_{n1} \end{pmatrix} + \dots + \alpha_n \begin{pmatrix} m_{1n} \\ \vdots \\ m_{nn} \end{pmatrix}$$

$$= \begin{pmatrix} \alpha_1 m_{11} + \alpha_2 m_{12} + \dots + \alpha_n m_{1n} \\ \vdots \\ \alpha_1 m_{n1} + \alpha_2 m_{n2} + \dots + \alpha_n m_{nn} \end{pmatrix} = \begin{pmatrix} \langle \text{1st row of } M, \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix} \rangle \\ \vdots \\ \langle \text{Nth row of } M, \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix} \rangle \end{pmatrix}$$

FOR THE EUCLIDEAN INNER PRODUCT

\therefore A LINEAR TRANSFORMATION CAN BE COMPUTED IN TERMS OF ITS REPRESENTATION AS $\begin{pmatrix} m_{11} & \dots & m_{1n} \\ \vdots & \ddots & \vdots \\ m_{n1} & \dots & m_{nn} \end{pmatrix}$ IN TERMS OF ITS EFFECTS OF THE (FIXED) BASIS VECTORS

SUCH A REPRESENTATION IS CALLED A MATRIX, AND IS SYMBOLIZED $M = (m_{ij})$

$(L_1 + L_2)(v) \equiv L_1(v) + L_2(v)$ BY THIS DEFINITION, LINEAR TRANSFORMATIONS (THUS MATRICES) FORM A GROUP
IT INDUCES $A + B = (a_{ij}) + (b_{ij}) = (a_{ij} + b_{ij}) = (c_{ij}) = C$ FOR MATRICES A, B, C

SIMILARLY $(\alpha L)(v) \equiv \alpha(L(v))$ BY THIS DEFINITION, LINEAR TRANSFORMATIONS AND MATRICES ARE RELATED TO THE UNDERLYING FIELD, AND BECOME THEMSELVES A VECTOR SPACE

$(L_1 L_2)(v) \equiv L_1(L_2(v))$ BY THIS DEFINITION, LINEAR TRANSFORMATIONS AND MATRICES ACQUIRE A MULTIPLICATION - TOGETHER WITH ADDITION AS ABOVE, THEY FORM A RING {IDENTITY AND INVERSES NOT YET DEFINED}

THIS INDUCES, FOR MATRICES A, B, C , $AB = (a_{ij})(b_{ij}) = (c_{ij}) = C$
HOW IS C_{ij} TO BE COMPUTED?

$$C = (c_{ij}) = \left(\langle \text{ith row of } A, \text{jth column of } B \rangle \right)$$

AN ISOMORPHISM BETWEEN RING/VECTOR SPACE OF LINEAR TRANSFORMATIONS AND OF MATRICES